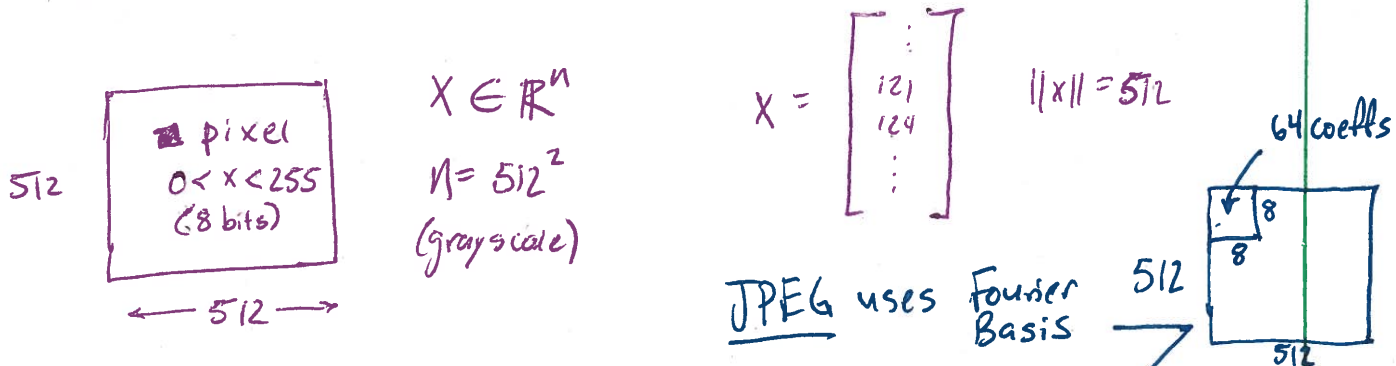
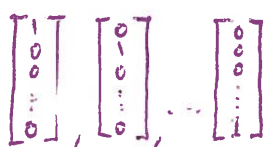


CHANGE OF BASIS, COMPRESSION OF IMAGES

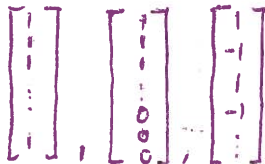
IMAGE COMPRESSION



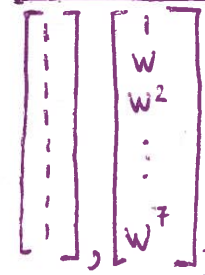
Standard Basis



Better Basis



Fourier Basis



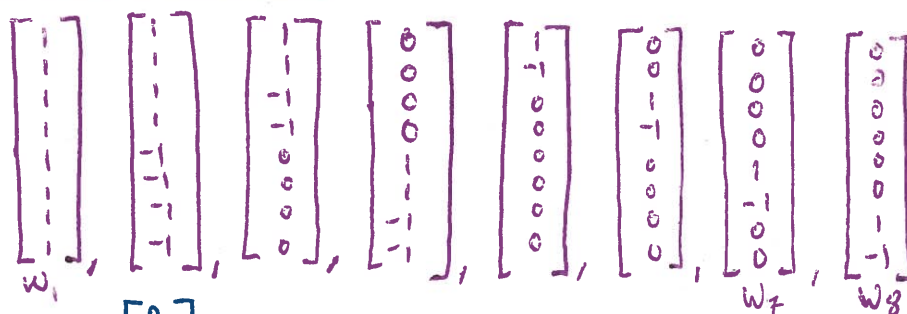
see lect 24

JPEG



Wavelet Basis  $\mathbb{R}^8$

(all vectors are orthogonal!)



So  $w^{-1}$  is fast!

$$p = \begin{bmatrix} p_1 \\ \vdots \\ p_8 \end{bmatrix} = c_1 w_1 + \dots + c_8 w_8 \quad (\text{change of basis})$$

$$= \begin{bmatrix} w \end{bmatrix} \begin{bmatrix} c \\ \vdots \end{bmatrix} \quad (p = wc \rightarrow c = w^{-1}p)$$

## CHANGE OF BASIS

Must Be: ① Fast      FFT (Fast Fourier Transform)  
                              FWT (Fast Wavelet Transform)

② Must be able to throw out a few basis vectors  
bc. a few accurately describe signal (compression)

Idea: Let columns of  $W$  = new basis vectors

$$\begin{bmatrix} x \end{bmatrix}_{\text{old basis}} \longrightarrow \begin{bmatrix} c \end{bmatrix}_{\text{new basis}} \quad \underline{x = Wc}$$

Given a linear transformation  $T$  ( $T: \mathbb{R}^n \rightarrow \mathbb{R}^n$ )

w/ respect to a basis  $v_1, \dots, v_n$  it has a matrix A

w/ respect to a basis  $w_1, \dots, w_n$  it has a matrix B

We will compute a transformation in these 2 bases, but there must be a connection between A and B. They are similar!

$$\text{SIMILAR: } B = M^{-1} A M$$

Where here, M is the change of basis matrix.

Notice, when ~~we~~<sup>we</sup> change basis  $(v, w)$ , every vector  $(x)$  has new coordinates  $(c)$

In these types of problems, a transformation matrix is given ( $T$ ) and the basis vectors  $(x)$ , we want to solve for matrix A so that

$$T = Ax$$

And A gives us a change of basis from  $T$  to  $x$

What is A? using basis  $v_1, \dots, v_8$

- We know  $T$  completely if we know how  $T$  behaves on the basis vectors. That is, we can solve for  $T$  in all space by knowing only 8 values,  $T(v_1), \dots, T(v_8)$ . We can do this because of linearity! Every vector is a linear combination of the basis vectors

- Because every

$$x = c_1 v_1 + c_2 v_2 + \dots + c_8 v_8$$

We know

$$T(x) = c_1 T(v_1) + \dots + c_8 T(v_8)$$

- So let's write

$$T(v_1) = a_{11} v_1 + a_{21} v_2 + \dots + a_{81} v_8$$

$$T(v_2) = a_{12} v_1 + a_{22} v_2 + \dots + a_{82} v_8$$

$$[A] = \begin{bmatrix} a_{11} & a_{21} & \dots \\ \vdots & \vdots & \dots \\ a_{81} & a_{82} & \dots \end{bmatrix}$$

so  $T = AV$   
↑ transformation vectors    ↓ basis vectors