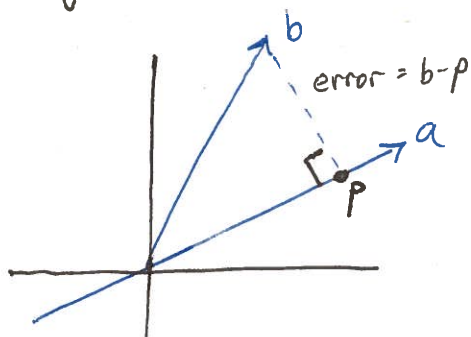


Projection, Least Squares, Projection Matrix

Projection:



In calculus the projection has trig function sol'n's in linear algebra the projection is a matrix: $p = a \frac{a^T b}{a^T a} = P b$

projection, p , is some multiple of a ,

$$p = x a$$

and $a \perp \text{error}$, $[a \cdot \text{error} = 0]$

$$a^T (b - x a) = 0$$

solve for x , projection mult of a ,

$$x = \frac{a^T b}{a^T a} \rightarrow p = a \frac{a^T b}{a^T a}$$

Projection matrix, P ,

$$P = \frac{a a^T}{a^T a}$$

so projection p is $p = P b$

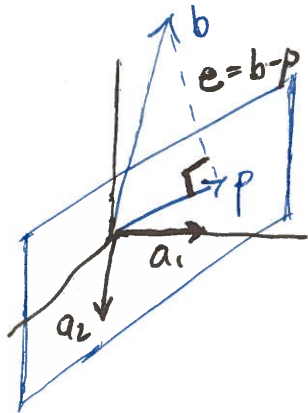
Notes about projection matrix, P :

- Column space $C(P)$ is a line through a
- $\text{rank}(P) = 1$, it's a line
- P is symmetric, $P^T = P$
- Projecting more than once produces no change, $P^2 = P$

Why use projection?

if $Ax = b$ has no solutions (say, more unknowns than eqns)
then we solve $A\hat{x} = p$ (p is projection of b into colspace of A)

Now consider 3-dimension case:



• project vector b into plane

• Describe plane using 2 basis vectors

$$\text{plane of } a_1, a_2 = \text{colspace of } A = \begin{bmatrix} \{ & \{ \\ a_1 & a_2 \\ \} & \} \end{bmatrix}$$

• error ($e = b - p$) is perpendicular to p

• projection, p , is some multiple of plane

$$p = \hat{x}_1 a_1 + \hat{x}_2 a_2 = A \hat{x}$$

Projection:

$$p = A \hat{x}, \text{ we want } \hat{x}$$

key is: error = $e = b - p = \underline{b - A \hat{x}}$ (error \perp plane)
 $[a \cdot \text{error} = 0]$

$$a_1^T (b - A \hat{x}) = 0$$

$$a_2^T (b - A \hat{x}) = 0$$

\downarrow $\leftarrow e$

$$A^T (b - A \hat{x}) = 0$$

e is in nullspace of A^T (from $A^T e = 0$)

$$\rightarrow e \perp C(A) !$$

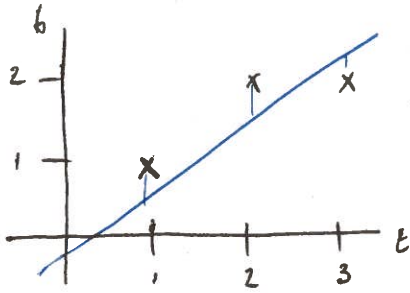
$$\hat{x} = (A^T A)^{-1} A^T b$$

$$\rightarrow p = A \hat{x} = A (A^T A)^{-1} A^T b$$

$$P = A (A^T A)^{-1} A^T$$

so $P = P b$

Least Squares (Fitting by a line)



$$b = C + Dt$$

$$C + D = 1$$

$$C + 2D = 2$$

$$C + 3D = 2$$

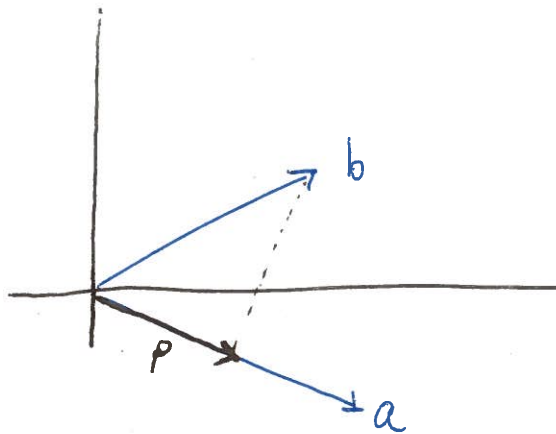
$$\begin{bmatrix} 1 & 1 \\ 1 & 2 \\ 1 & 3 \end{bmatrix} \begin{bmatrix} C \\ D \end{bmatrix} = \begin{bmatrix} 1 \\ 2 \\ 2 \end{bmatrix}$$

$A \quad x = b$

So, we can't solve $Ax=b$, but we can solve
the next best thing, $Ax = p \dots A^T Ax = A^T b$

The DOT PRODUCT in Matrix notation

$$a \cdot b = B^T A$$



given 2 vectors, a & b
the projection of a onto b
is given by the dot product

$$a \cdot b = |a||b| \cos \theta$$

Say $\Rightarrow a = (1, 2, 4) \quad b = (-2, 4, -1)$

$$\begin{aligned} \text{then } a \cdot b &= 1 \cdot (-2) + 2 \cdot 4 + 4 \cdot (-1) \\ &= -2 + 8 - 4 \\ &= 2 \end{aligned}$$

In matrix form,

$$A = \begin{bmatrix} 1 \\ 2 \\ 4 \end{bmatrix}, \quad B = \begin{bmatrix} -2 \\ 4 \\ -1 \end{bmatrix}$$

$$B^T A = \begin{bmatrix} -2 & 4 & -1 \end{bmatrix} \begin{bmatrix} 1 \\ 2 \\ 4 \end{bmatrix}$$

$$= -2 + 8 - 4$$

$$= 2$$